

$$1. (1) Q_1 = (K^P + L^P)^{1/P}$$

$$Q_2 = [(2K)^P + (2L)^P]^{1/P} = 2Q_1$$

$$(2) MP_L = \frac{\partial Q}{\partial L} = L^{P-1} (K^P + L^P)^{\frac{1-P}{P}}$$

$$MP_K = \frac{\partial Q}{\partial K} = K^{P-1} (K^P + L^P)^{\frac{1-P}{P}}$$

$$(3) MRTS_{L,K} = \frac{MP_L}{MP_K} = (L/K)^{P-1}$$

$$(4) E_L = \frac{\partial Q / \partial L}{w_L / L} = L^P (K^P + L^P)^{-1}$$

$$E_K = \frac{\partial Q / \partial K}{w_K / K} = K^P (K^P + L^P)^{-1}$$

$$E_L + E_K = 1$$

$$(5) L' = \frac{1}{2} Q \quad K' = \frac{1}{2} Q$$

$$Q' = \frac{1}{2} Q \quad Q_1 = Q_2 = Q'$$

$$Q_1 + Q_2 = Q$$

$$2. (1) TC = A + L + b_2$$

$$Q = A^{1/4} L^{1/4} 16^{1/4}$$

$$\begin{cases} \text{Min } TC = A + L + b_2 \\ \text{s.t. } Q = 4A^{1/4} L^{1/4} \end{cases}$$

$$\begin{cases} \frac{\partial Y}{\partial A} = 0 \\ \frac{\partial Y}{\partial L} = 0 \\ \frac{\partial Y}{\partial b_2} = 0 \end{cases} \quad \text{解得} \quad \begin{cases} A = L \\ A = \frac{1}{4}L^2 \end{cases}$$

$$\therefore TC = \frac{1}{8} Q^2 + 32$$

$$TC = \frac{1}{8} Q + 32$$

$$(2) TVC = \frac{1}{8} Q^2$$

$$AVC = \frac{1}{8} Q$$

$$(3) MCL = \frac{\partial TC}{\partial Q} = \frac{1}{4} Q$$

$$3. (1) LRTC(Q) = L + 4K$$

$$Q = L^{2/3} K^{1/3}$$

$$\begin{cases} \text{Min } LRTC(L, K) = L + 4K \\ \text{s.t. } Q = L^{2/3} K^{1/3} \end{cases}$$

$$\begin{cases} \frac{\partial Y}{\partial K} = 0 \\ \frac{\partial Y}{\partial L} = 0 \\ \frac{\partial Y}{\partial b} = 0 \end{cases} \quad \text{解得} \quad \begin{cases} L = 8K \\ L = 2Q \end{cases}$$

$$\therefore LRTC(Q) = 2Q + Q = 3Q$$

(3) 短期内，厂商只能调节劳动投入但不能调节资本投入，因此短期内的成本函数是厂商在既定资本水平下的最低成本；而长期内，厂商既可以调节劳动投入，又可以调节资本投入，因此长期的成本函数是厂商在最优生产规模下的最低成本。从几何上说，厂商的长期成本曲线是短期成本曲线的包络线。因此对于既定的产量，长期成本小于等于短期成本。

$$4. (1) \begin{cases} \text{Min } w_1 x_1 + w_2 x_2 \\ \text{s.t. } y = x_1^a x_2^b \end{cases}$$

$$d = w_1 x_1 + w_2 x_2 - \lambda (y - x_1^a x_2^b)$$

$$\begin{cases} \frac{\partial d}{\partial x_1} = w_1 - \lambda a x_1^{a-1} x_2^b = 0 \\ \frac{\partial d}{\partial x_2} = w_2 - \lambda b x_1^a x_2^{b-1} = 0 \end{cases}$$

$$\frac{\partial d}{\partial \lambda} = y - x_1^a x_2^b = 0$$

$$\text{解得} \quad \begin{cases} x_1 = (\frac{w_1 a}{w_2 b})^{\frac{1}{a+b}} y^{\frac{1}{a+b}} \\ x_2 = (\frac{w_2 b}{w_1 a})^{\frac{1}{a+b}} y^{\frac{1}{a+b}} \end{cases}$$

$$(2) y = x_1^a x_2^b$$

$$x_i = (\frac{y}{k^b})^{\frac{1}{a}}$$

$$TC = w_1 (\frac{y}{k^b})^{\frac{1}{a}} + w_2 k$$

$$AC = w_1 k^{-\frac{1}{a}} y^{\frac{1}{a}-1} + \frac{w_2 k}{y}$$

$$AVC = w_1 k^{-\frac{1}{a}} y^{\frac{1}{a}-1}$$

$$ATC = \frac{w_2 k}{y}$$

$$5. (1) TCA = 8^2 + 50 = 114$$

$$TCB = \frac{1}{2} \times 8^2 + 2 \times 8 + 80 = 128$$

114 < 128  $\therefore$  选方案 A

$$(2) TCB \leq TCA$$

$$\Delta TC = TCB - TCA = -\frac{1}{2} Q^2 + 2Q + 30$$

$$\Delta TC \leq 0 \quad \text{解得 } Q \geq 10$$

$$(3) MCA = MCB \text{ 且 } TC \text{ 最小}$$

$$MCA = \frac{\partial TCA}{\partial Q_A} = 2Q_A$$

$$MCB = \frac{\partial TCB}{\partial Q_B} = Q_B + 2$$

$$\begin{cases} Q_A + Q_B = 22 \\ 2Q_A = Q_B + 2 \end{cases} \quad \text{解得} \quad \begin{cases} Q_A = 8 \\ Q_B = 14 \end{cases}$$

$$TC = 114 + (\frac{1}{2} \times 14^2 + 2 \times 14 + 80) = 320$$

$$(2) Q = L^{2/3} K_s^{1/3}$$

$$L = Q^{2/3} K_s^{-1/3}$$

$$SRTC(L, K_s) = L + 4K_s = Q^{2/3} K_s^{1/3} + 4K_s$$